

# TRANSFORMASI FOURIER


SISTEM KOMUNIKASI  
Semester Ganjil 2016/2017  
Program Studi S1 Teknik Telekomunikasi  
Universitas Telkom

# FUNGSI & DEFINISI

- ◉ Fungsi Transformasi Fourier yaitu utk menganalisis bentuk spektral [ $S(f)$ ] dari suatu sinyal kawasan waktu [ $s(t)$ ]
- ◉ Fungsi Inverse Transformasi Fourier yaitu utk menganalisis bentuk sinyal kawasan waktu [ $s(t)$ ] jika sinyal tersebut memiliki bentuk spektral [ $S(f)$ ]


# FORMULA TRANSFORMASI FOURIER

## Transformasi fourier

$$S(f) = \int_{-\infty}^{\infty} s(t) \cdot e^{-j2\pi ft} dt$$


$S(f)$  adalah hasil transformasi fourier dari sinyal dalam domain waktu  $s(t)$

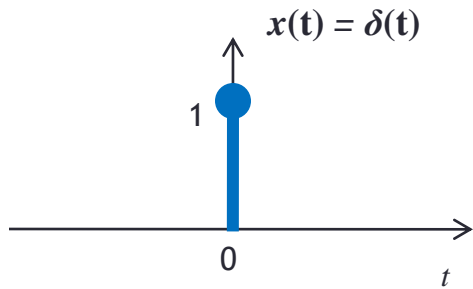
## Inverse Transformasi Fourier

$$s(t) = \int_{-\infty}^{\infty} S(f) \cdot e^{j2\pi ft} df$$


Jika Transformasi Fourier  $S(f)$  suatu sinyal diketahui maka bisa didapatkan kembali persamaan sinyal dalam domain waktu  $s(t)$  dengan formula Inverse Transformasi Fourier

# BEBERAPA TRANSFORMASI PENTING

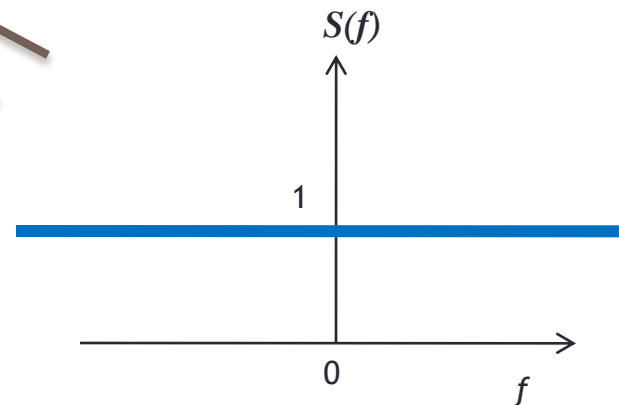
## 1. Sinyal Delta Diract/ Impuls



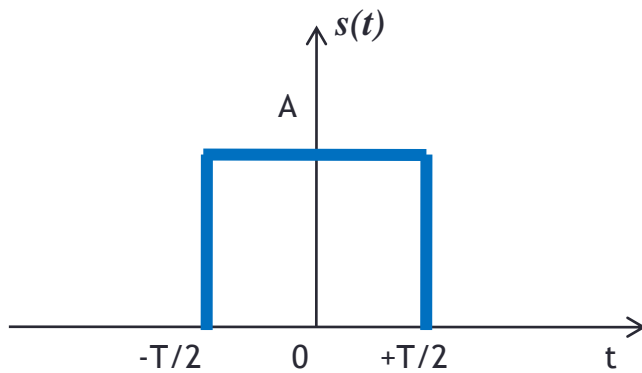
$$S(f) = \int_{-\infty}^{\infty} \delta(t) \cdot e^{-j2\pi ft} dt = 1$$

Transformasi Fourier

Inverse Transformasi Fourier



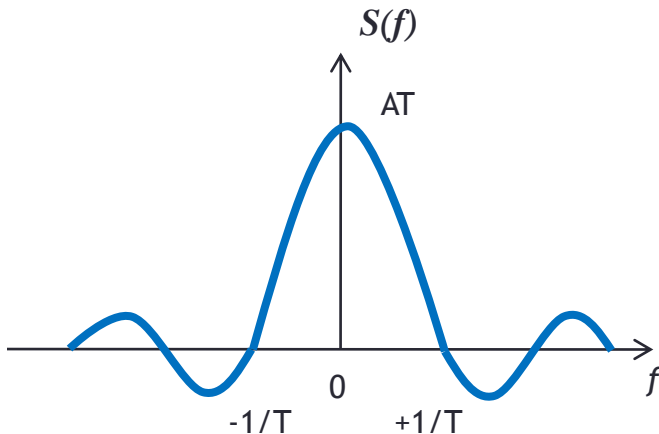
## 2. Sinyal Rectangular/ Pulsa



Transformasi Fourier

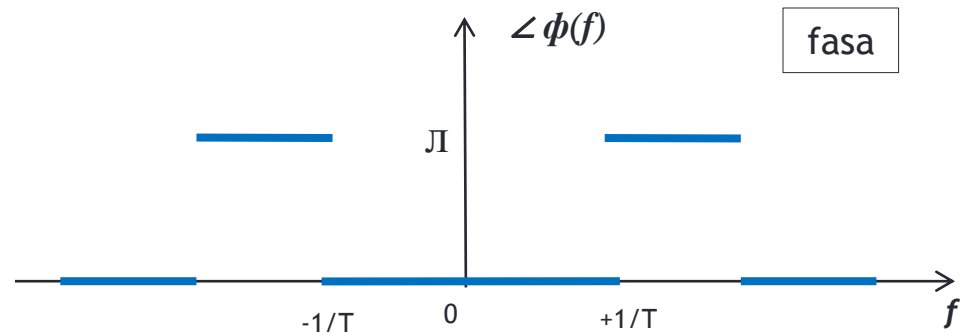
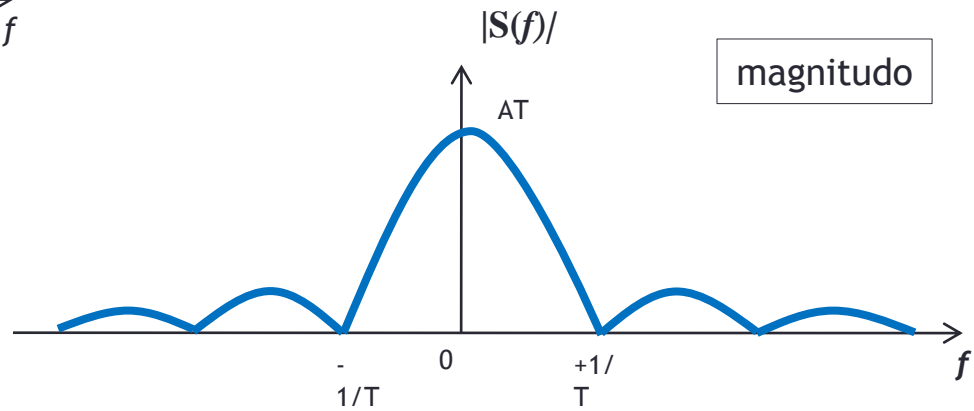
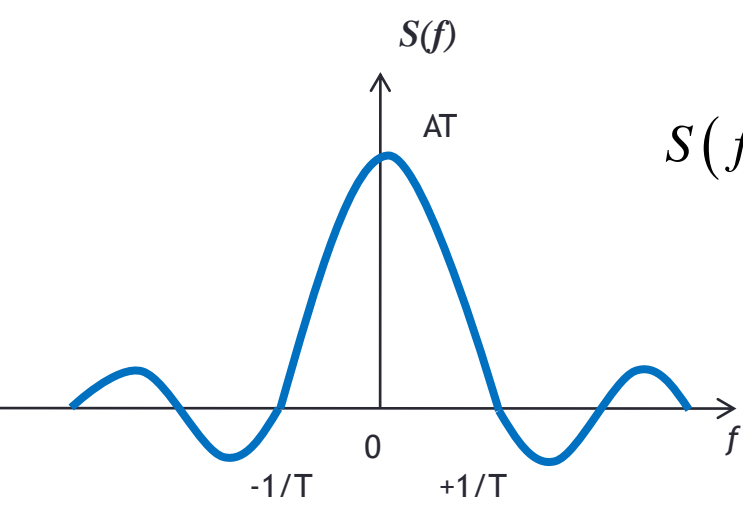


Inverse Transformasi Fourier



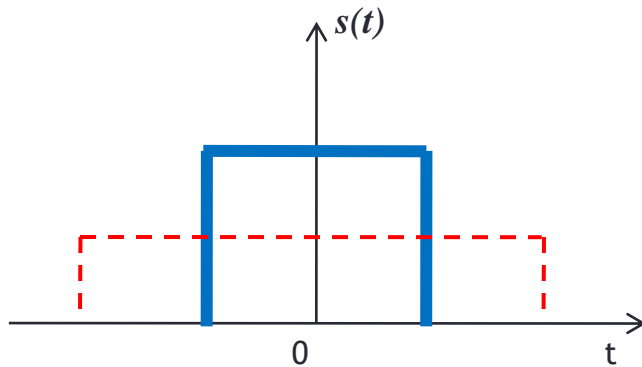
$$\begin{aligned}
 S(f) &= \int_{-T/2}^{T/2} A e^{-j2\pi f t} dt \\
 &= \frac{A}{-j2\pi f} \left[ e^{-j2\pi f t} \right]_{-T/2}^{T/2} \\
 &= \frac{A}{-j2\pi f} \left[ e^{-j2\pi f T/2} - e^{j2\pi f T/2} \right] \\
 &= \frac{A}{j2\pi f} \left[ e^{j2\pi f T/2} - e^{-j2\pi f T/2} \right] \\
 &= \frac{A}{\pi f} \frac{1}{2j} \left[ e^{j2\pi f T/2} - e^{-j2\pi f T/2} \right] \\
 &= \frac{A}{\pi f} \sin \pi f T \\
 &= \frac{A}{1/T} \frac{\sin(\pi f T)}{\pi f T} \\
 &= AT \cdot \text{sinc}(\pi f T)
 \end{aligned}$$

$$S(f) = AT \cdot \text{sinc}(\pi fT)$$



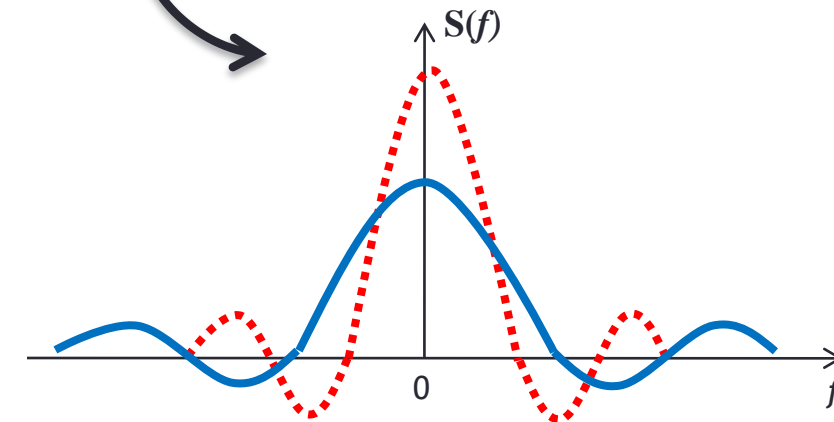
# SIFAT-SIFAT TRANSFORMASI FOURIER

## a. Time Scaling



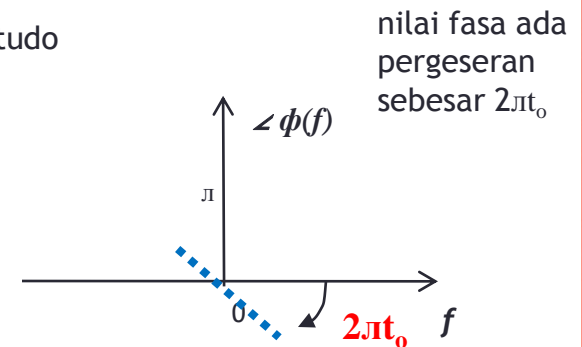
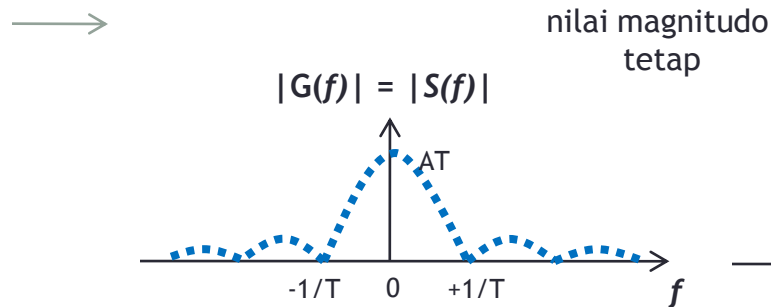
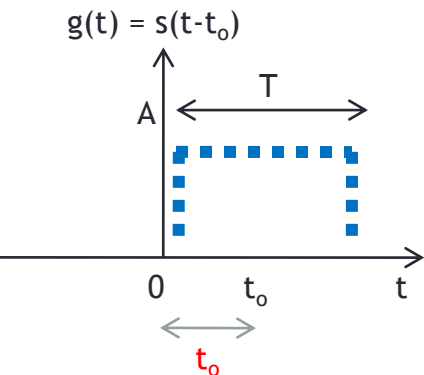
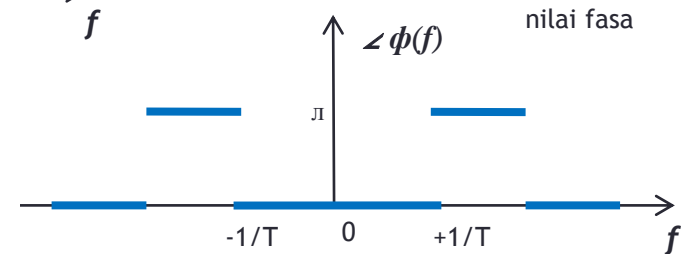
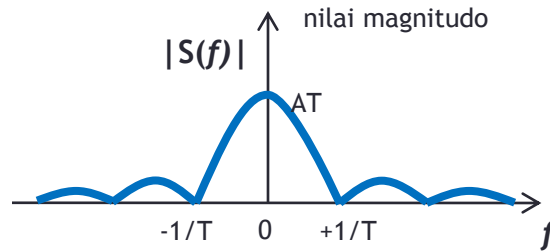
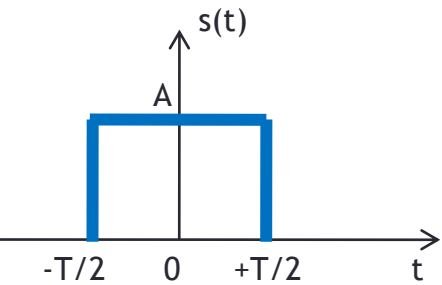
Jika:  $s(t) \square S(f)$

Maka:  $s(at) \square \frac{1}{|a|} \cdot S\left(\frac{f}{a}\right)$



## b. Time Shift

Jika  $s(t) \leftrightarrow S(f)$   
 maka  $s(t-t_0) \leftrightarrow S(f) e^{-j2\pi f t_0}$



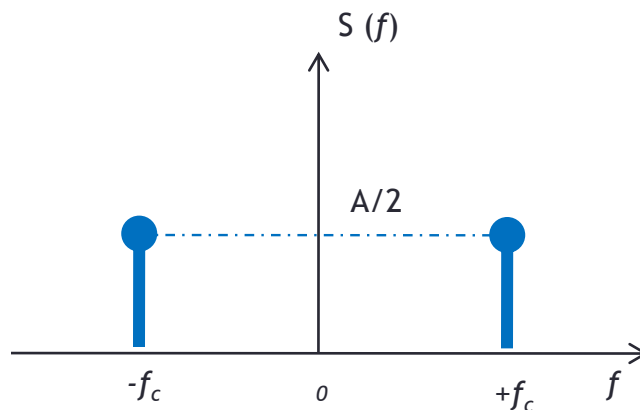


### c. Frequency Shift

Jika  $s(t) \longleftrightarrow S(f)$  maka  $S(f-f_0) \longleftrightarrow s(t) e^{-j2\pi f_0 t}$

Contoh:  $s(t) = A \cdot \cos 2\pi f_c t = \frac{A}{2} \left( e^{i2\pi f_c t} + e^{-j2\pi f_c t} \right)$

maka  $S(f) = \frac{A}{2} \delta(f + f_c) + \frac{A}{2} \delta(f - f_c)$



#### d. Transformasi Fourier Sinyal Periodik

Jika  $x(t) \longleftrightarrow X(f)$  untuk sinyal non-periodik,

Maka

$$x_p(t) = \sum_{n=-\infty}^{+\infty} x(t - nT_o)$$

$x_p(t)$  sinyal periodik  
dengan periode  $T_o$

Transformasi Fourier



Inverse Transformasi Fourier

$$X_p(f) = \frac{1}{T_o} \sum_{m=-\infty}^{+\infty} X\left(\frac{m}{T_o}\right) \cdot \delta\left(f - \frac{m}{T_o}\right)$$

e. Integrasi pada kawasan waktu

Bila  $s(t) \longleftrightarrow S(f)$ , kemudian menghasilkan  $S(0) = 0$ , maka

$$\int_{-\infty}^t s(t) \cdot dt \leftrightarrow \frac{1}{j2\pi f} \cdot S(f)$$

f. Diferensiasi pada kawasan waktu

Bila  $s(t) \longleftrightarrow S(f)$ , Jika pada kawasan waktu dilakukan diferensiasi sekali maka:

$$\frac{d}{dt} s(t) \leftrightarrow j2\pi f \cdot S(f)$$

g. Konvolusi pada kawasan waktu

Jika  $s_1(t) \leftrightarrow S_1(f)$  dan  $s_2(t) \leftrightarrow S_2(f)$ , maka

$$\int_{-\infty}^{\infty} s_1(t) \cdot s_2(t - \tau) d\tau \leftrightarrow S_1(f) \cdot S_2(f)$$

h. Perkalian pada kawasan waktu

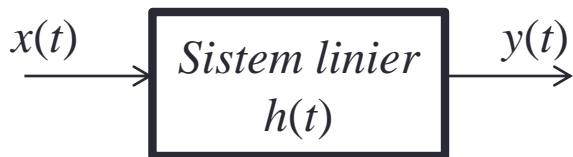
Jika  $s_1(t) \leftrightarrow S_1(f)$  dan  $s_2(t) \leftrightarrow S_2(f)$ , maka

$$s_1(t) \cdot s_2(t) \leftrightarrow \int_{-\infty}^{\infty} S_1(\lambda) \cdot S_2(f - \lambda) d\lambda$$

# TRANSMISI SINYAL MELALUI SISTEM LINIER

Respon waktu:

time domain

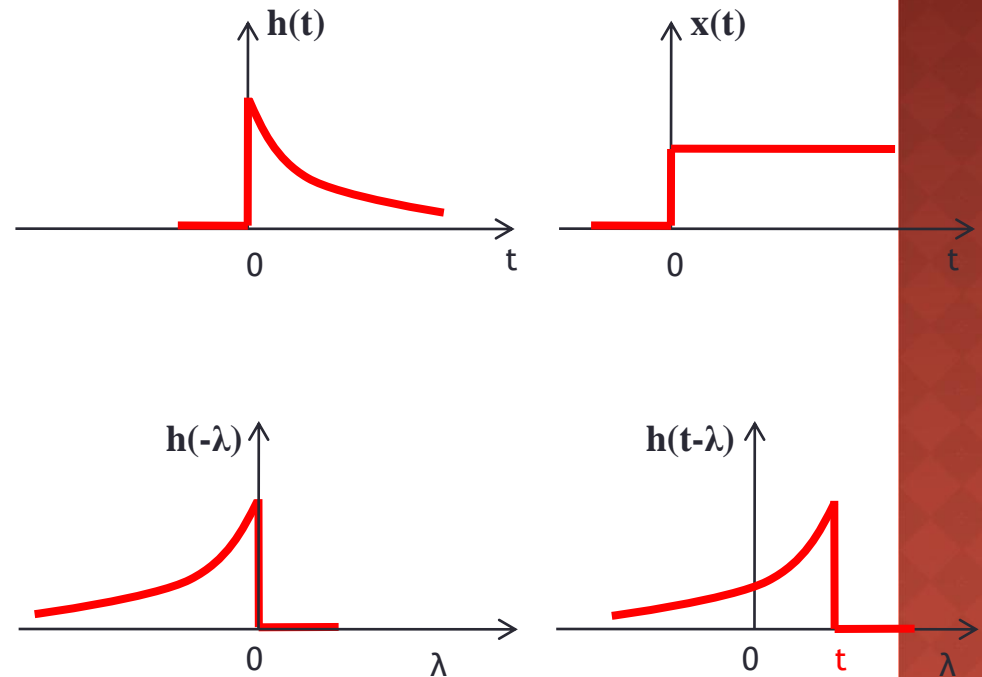


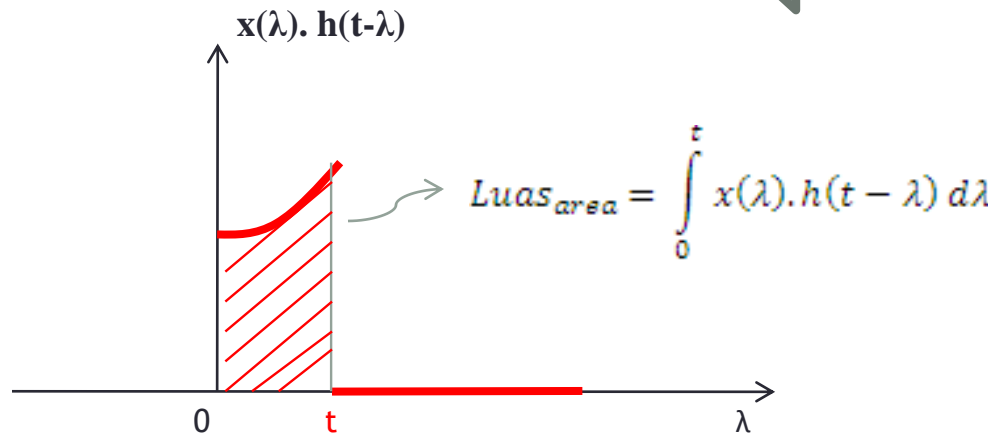
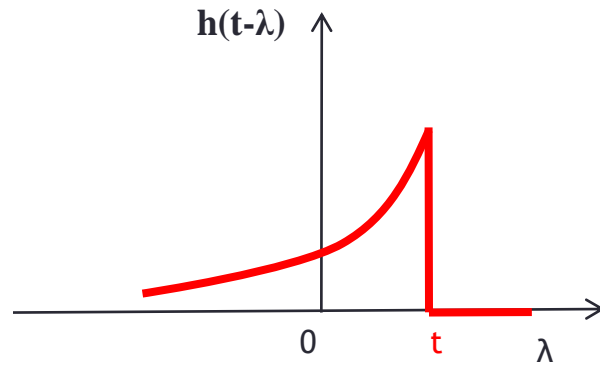
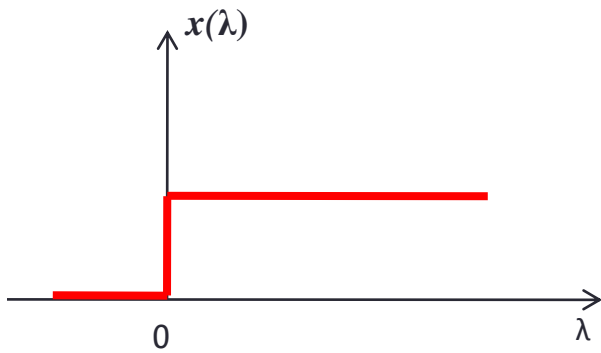
$h(t) \Xi$  respon impuls

$$\begin{aligned} y(t) &= \int_{-\infty}^{\infty} h(\lambda) \cdot x(t - \lambda) \cdot d\lambda \\ &= \int_{-\infty}^{\infty} x(\lambda) \cdot h(t - \lambda) \cdot d\lambda \\ &= x(t) \otimes h(t) \\ &= h(t) \otimes x(t) \end{aligned}$$

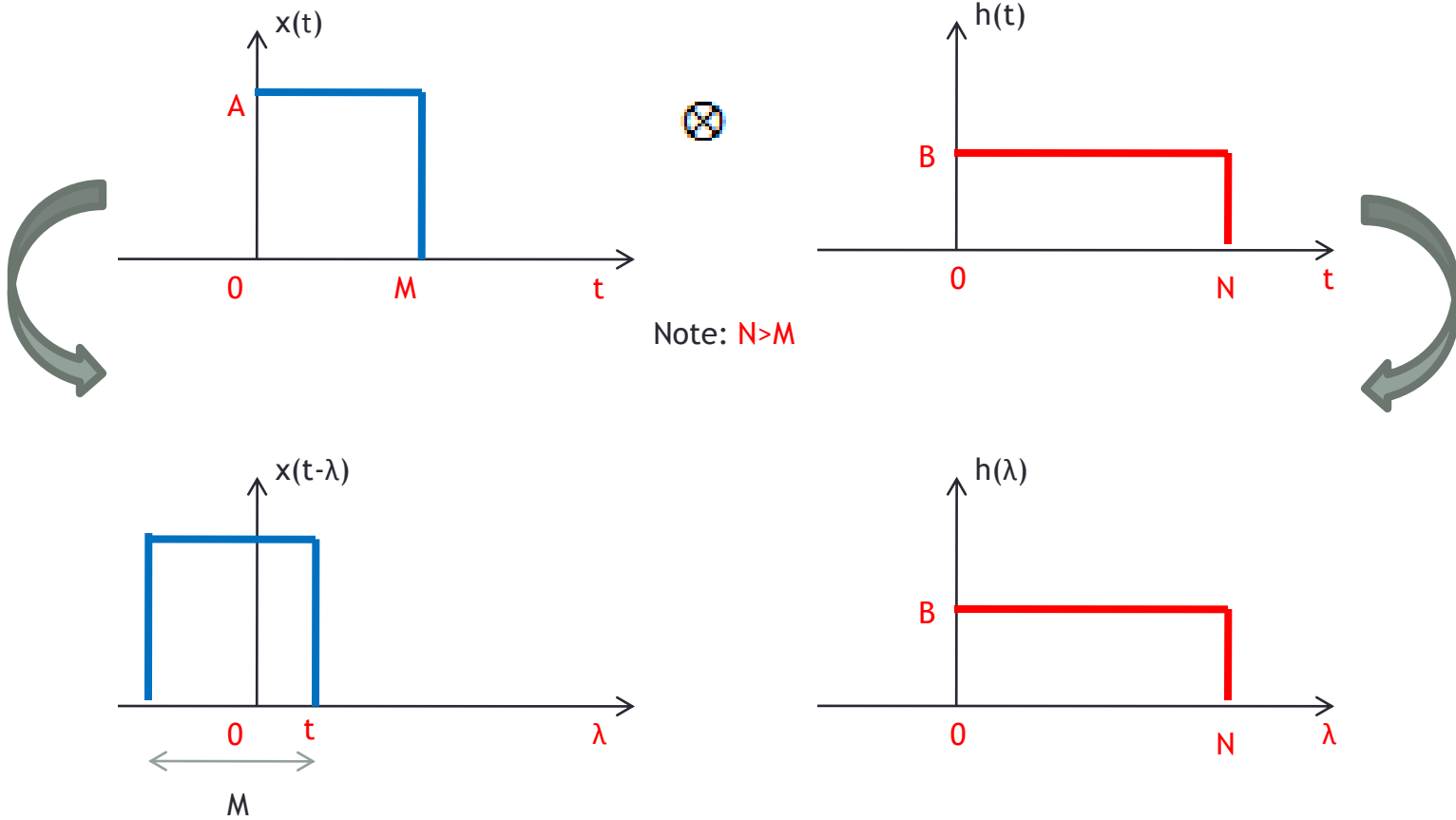
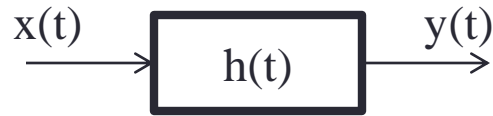
**Contoh:** perhitungan konvolusi, representasi grafis

[1]

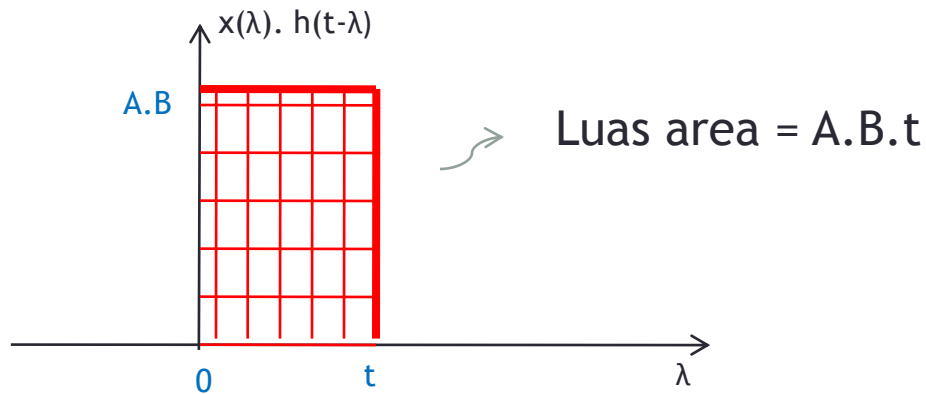




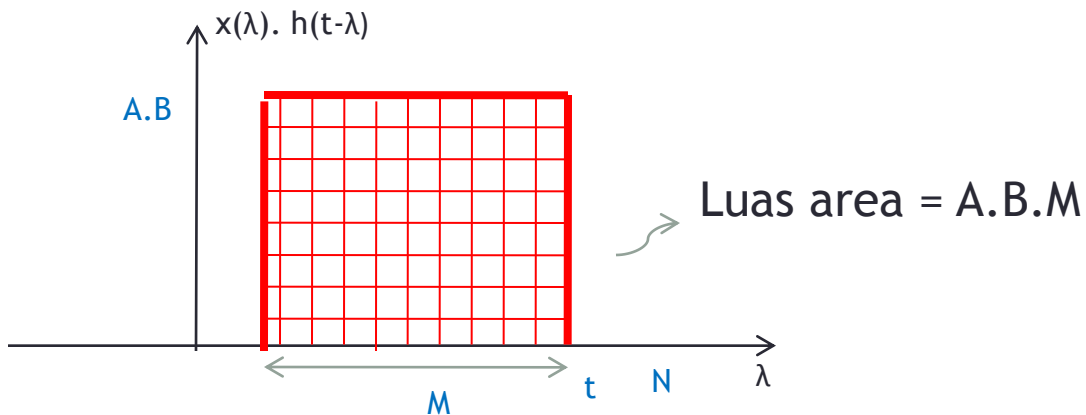
[2]



Untuk  $0 \leq t \leq M$ , maka:

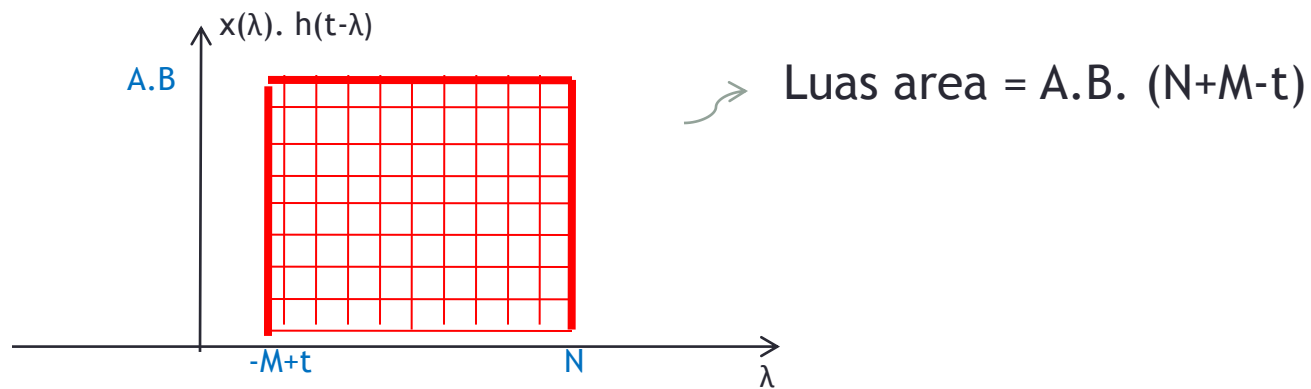


Untuk  $M < t \leq N$ , maka:

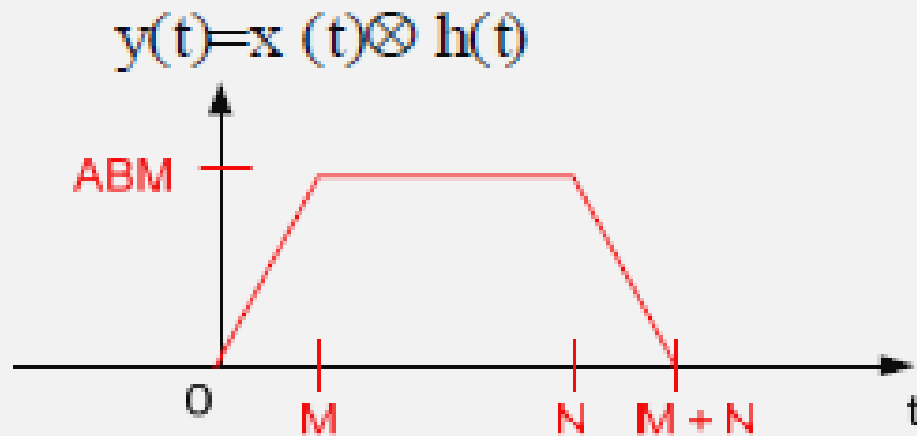




Untuk  $t \geq N$ , maka:



Sehingga:

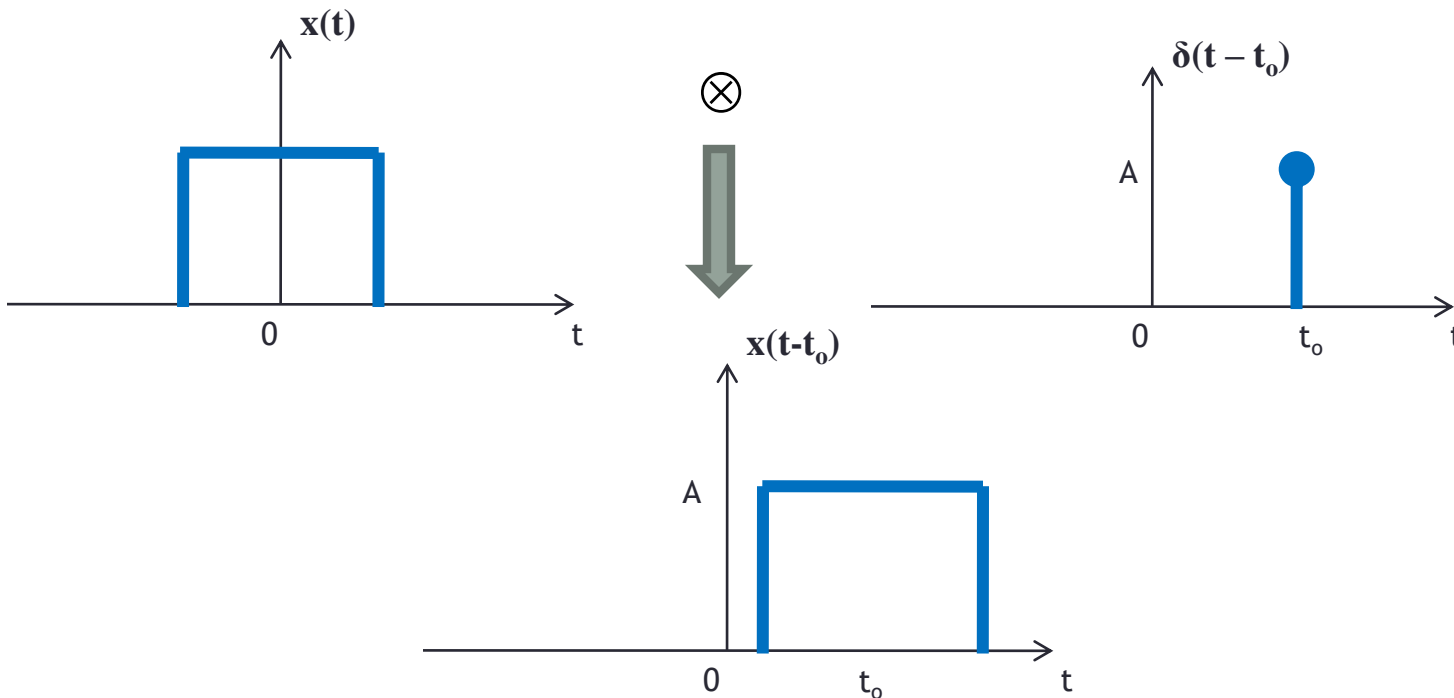


# KASUS KHUSUS

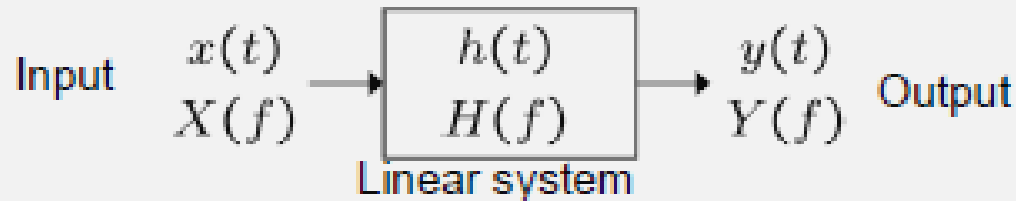
Konvolusi dengan fungsi  $\delta(t-t_0)$

$$x(t) \otimes \delta(t-t_0) = \int_{-\infty}^{\infty} x(t-\lambda) \cdot \delta(t-t_0) d\lambda = x(t-t_0)$$

$$x(t) \otimes A \cdot \delta(t-t_0) = A \cdot x(t-t_0)$$

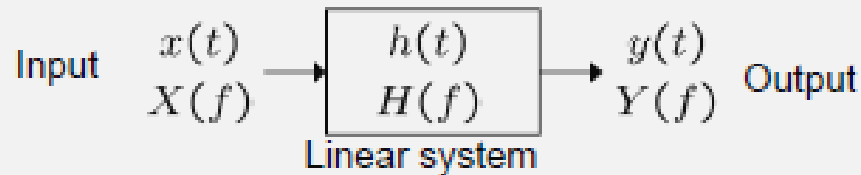


# TRANSMISI SINYAL MELALUI SISTEM LINIER



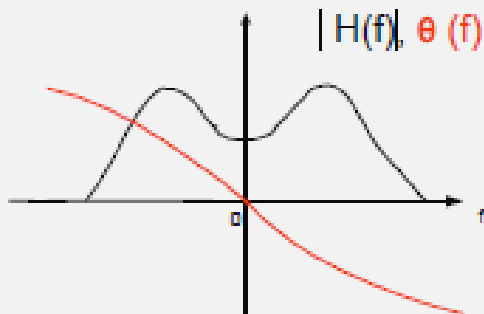
- Deterministic signals:  $Y(f) = X(f)H(f)$
- Random signals:  $G_Y(f) = G_X(f)|H(f)|^2$
- $Y(f)$  = Sinyal output dalam domain frekuensi
- $X(f)$  = Sinyal input dalam domain frekuensi
- $H(f)$  = Respons frekuensi sistem linier
- $G_Y(f)$  = PSD (Power Spectral Density) sinyal output
- $G_X(f)$  = PSD (Power Spectral Density) sinyal input

# Sistem Lowpass vs Bandpass

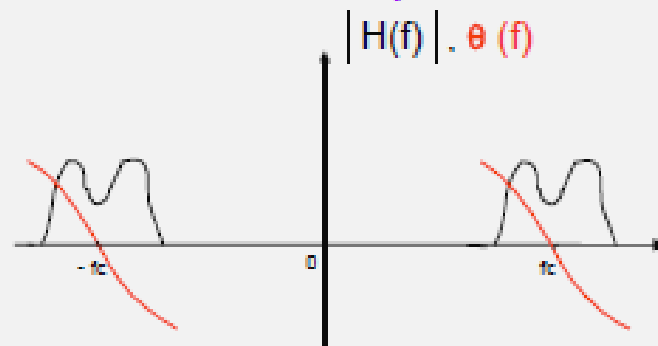


Jika  $h(t)$  riil  $\Rightarrow H(f)$  kompleks  $\rightarrow |H(f)|$  merupakan fungsi genap  
 $\rightarrow \theta(f)$  merupakan fungsi ganjil

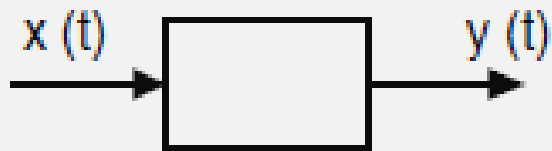
## Sistem "lowpass"



## Sistem "bandpass"

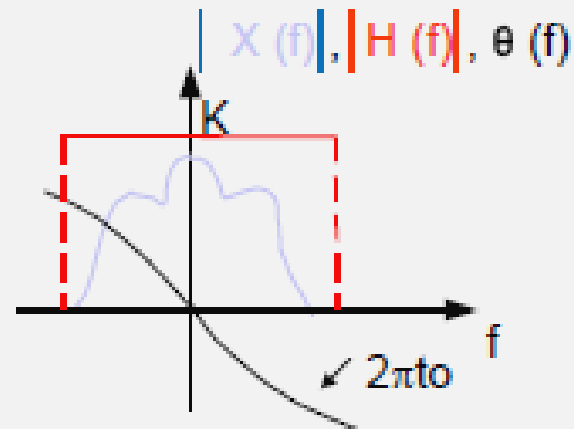


## Kondisi “distortionless transmission”

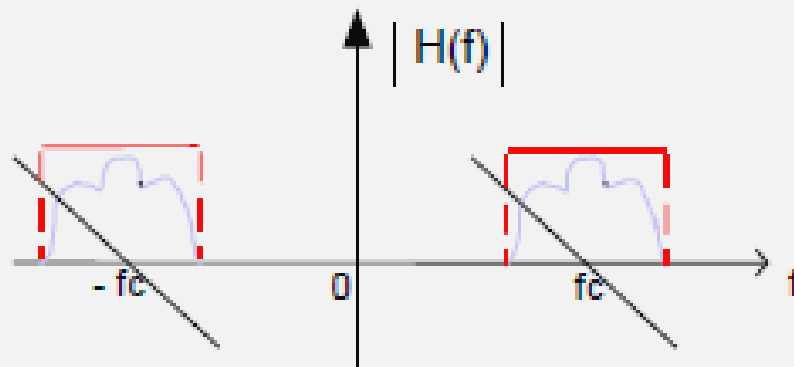


$$y(t) = K \cdot X(t - t_0)$$

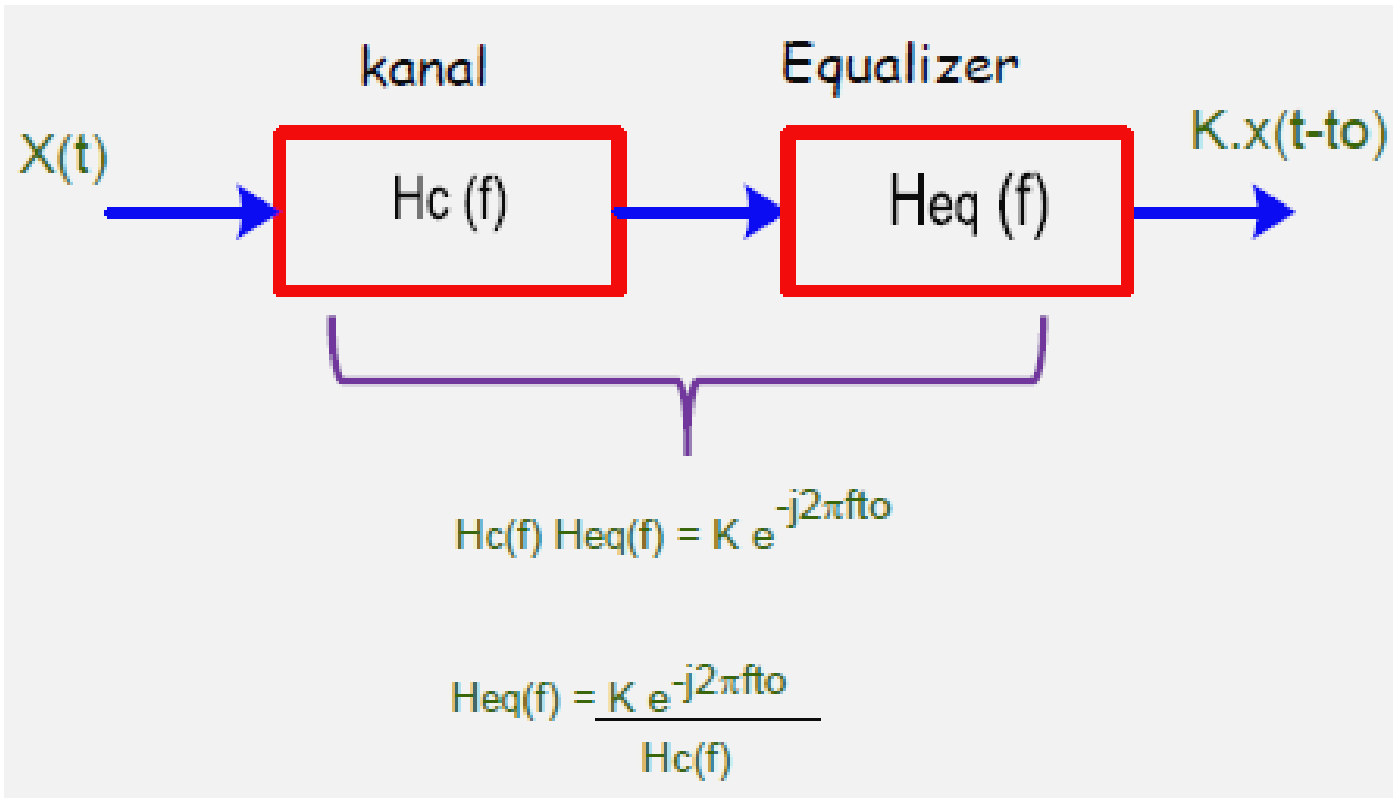
$$H(f) = K e^{-j2\pi f t_0}$$



• Untuk sistem “bandpass”

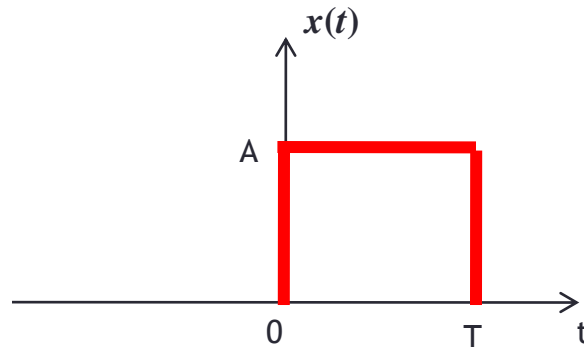


## Kondisi “distorsi linier” dan Prinsip Ekualisasi Kanal



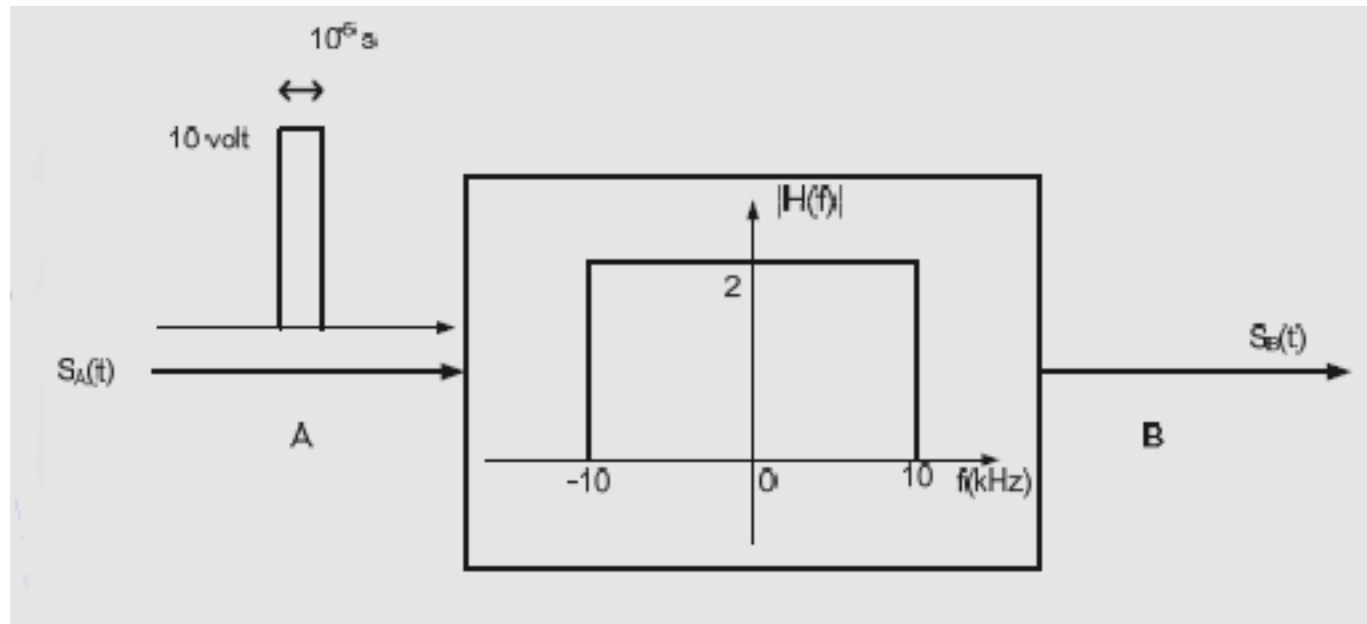
# LATIHAN SOAL

[1] Perhatikan gambar sinyal  $x(t)$  *dibawah ini*:



- Tentukan  $X(f)$  yang merupakan transformasi fourier dari sinyal tersebut !
- Jika sinyal  $z(t) = x(t) * y(t)$ , dimana  $y(t) = \cos(4\pi t/T)$ , tentukan  $Z(f)$

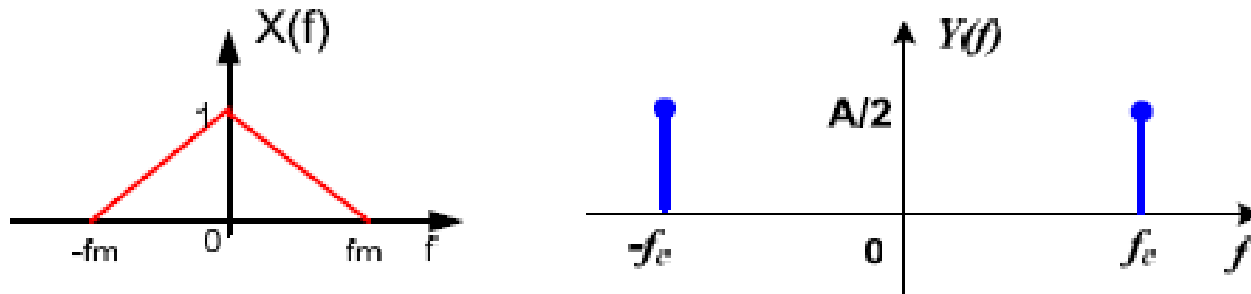
[2] Suatu sinyal memasuki sistem yang diwakili oleh LPF berikut ini:



Tentukan  $S_A(f)$  ,  $S_B(f)$  ,  $S_B(t)$  !

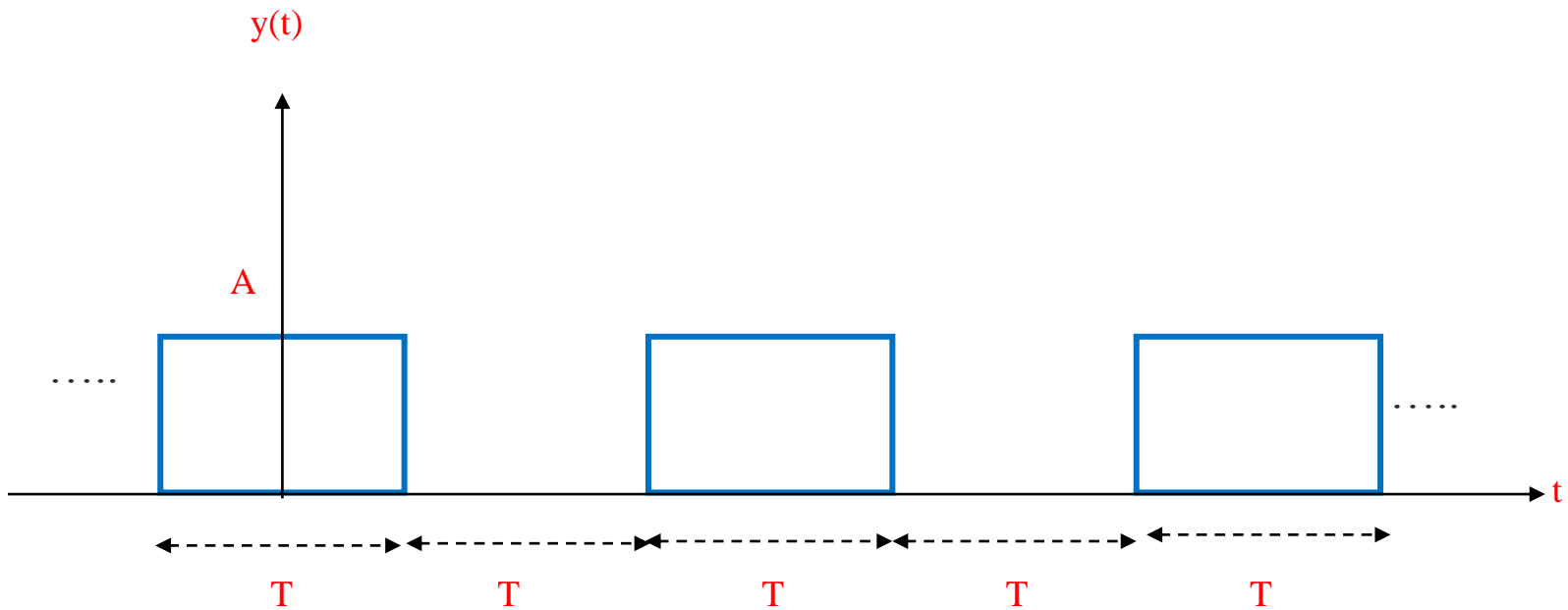


[3] Diketahui sinyal dalam domain frekuensi sebagai berikut:

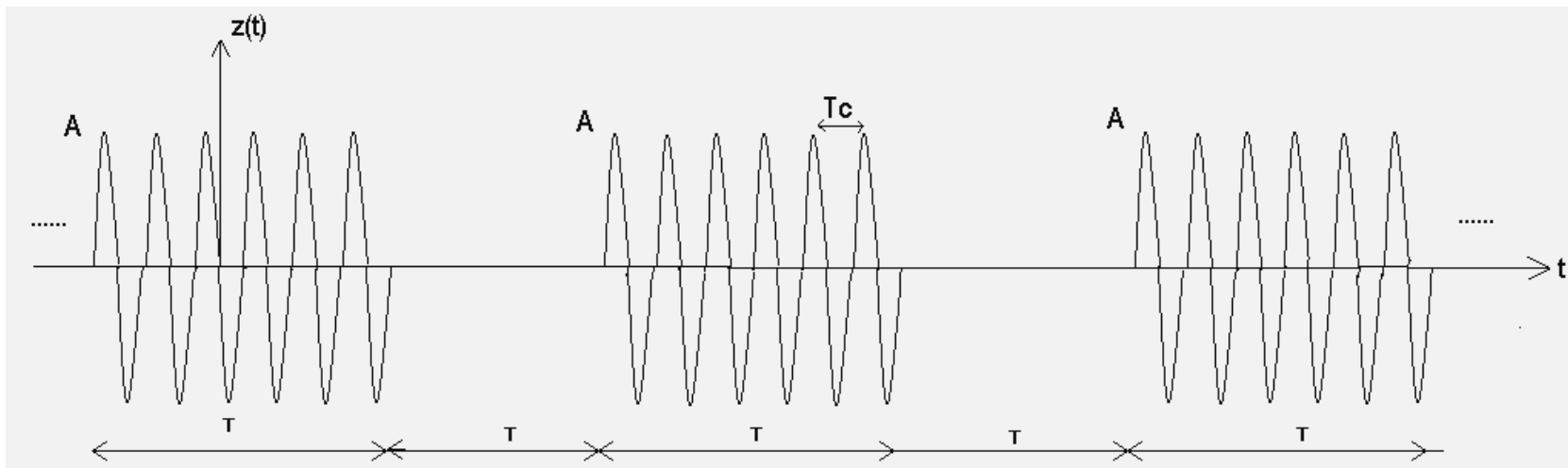


Untuk  $f_c > f_m$ , Gambarkan  $Z(f) = X(f) * Y(f)$  !

**[4]** Tentukanlah  $Y(f)$  dan gambarkan jika diketahui gambar  $y(t)$  berikut ini!



**[5]** Tentukanlah  $Z(f)$  dan gambarkan jika diketahui gambar  $z(t)$  berikut ini!



END